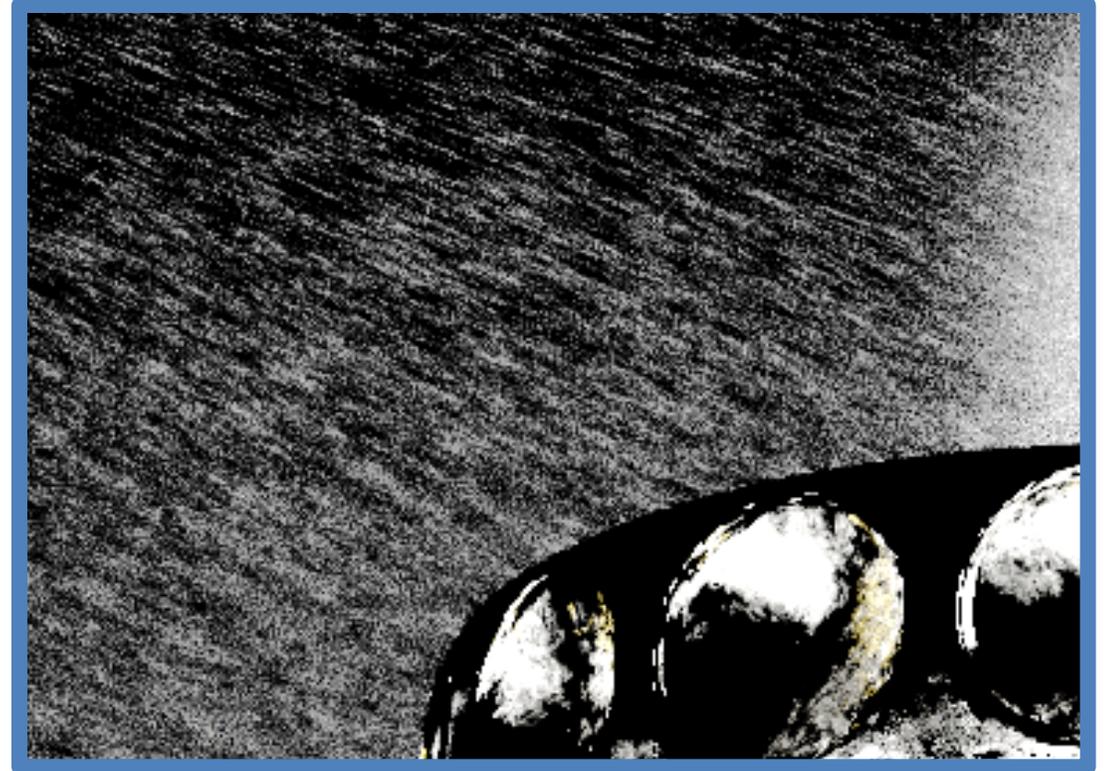


Johannes Hanika, Anton Kaplanyan, and Carsten Dachsbacher

# Improved half vector space light transport

# Motivation

- ▶ rendering images with half vector space light transport [KHD14]



- ▶ uneven exploration of certain flat areas *despite* explicit stratification!

# Motivation

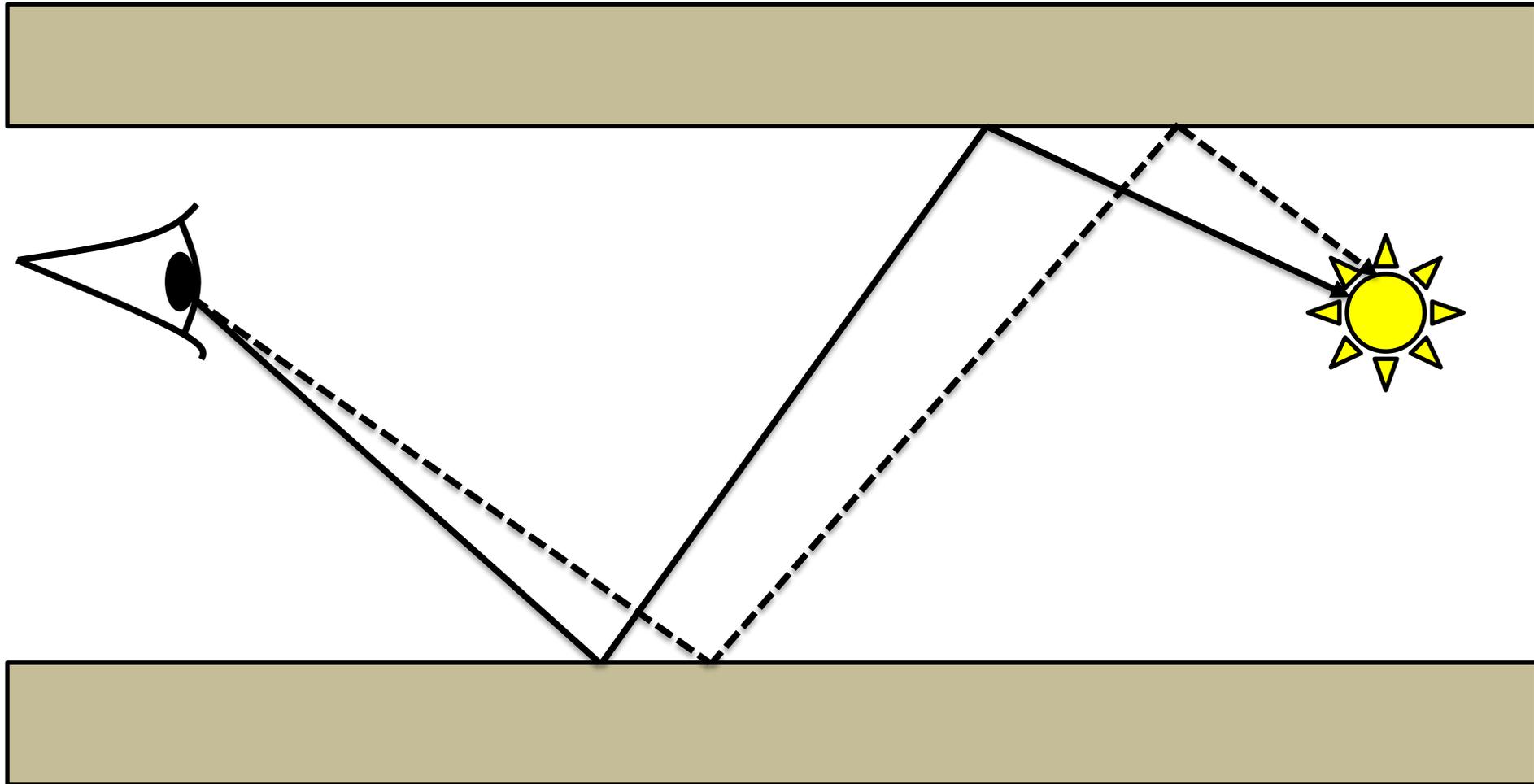
- ▶ rendering images with half vector space light transport [KHD14]



- ▶ HSLT is confused about highly displaced meshes!

# Quick summary on Metropolis light transport

- ▶ Markov chain: sample tentative new state (path)
- ▶ perturb current path
- ▶ accept with certain probability to maintain detailed balance

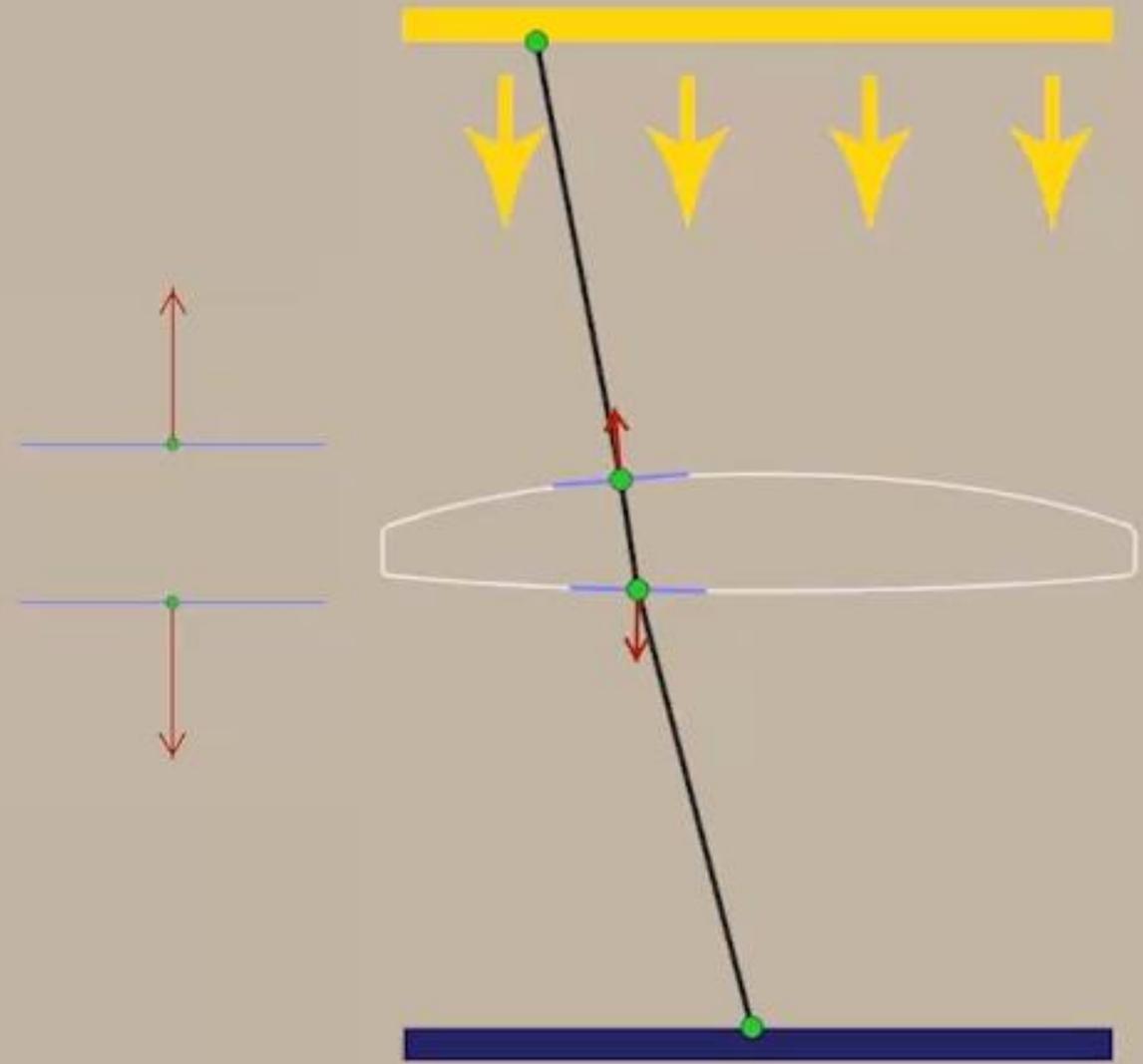


# Veach's Metropolis light transport

- ▶ collection of mutation strategies
- ▶ all converted into common measure (product vertex area measure) for comparison
- ▶ rely on small mutation steps to meet
  - ▶ BSDF constraints (angular, half vectors)
  - ▶ geometry constraints (vertex location, e.g. point on light source or key holes)
- ▶ explicit control over these constraints?

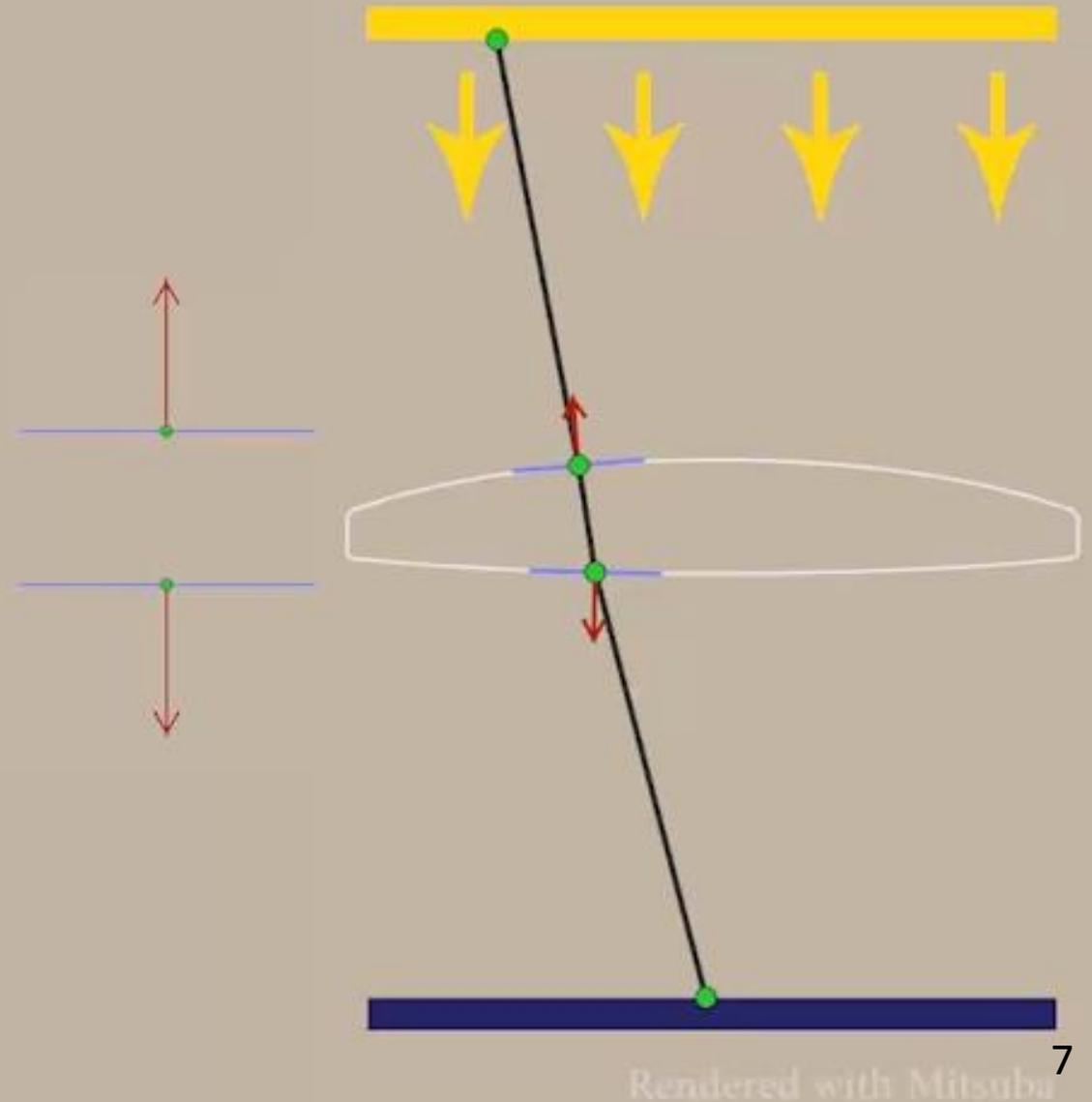
# Manifold exploration [JM12] and specular constraints

- ▶ two endpoints with specular **hard constraints**
- ▶ move end point, keep constraints satisfied



# Half vector space light transport [KHD14]

- ▶ rough scattering: use **soft constraints**
- ▶ keep end points fixed, change half vectors



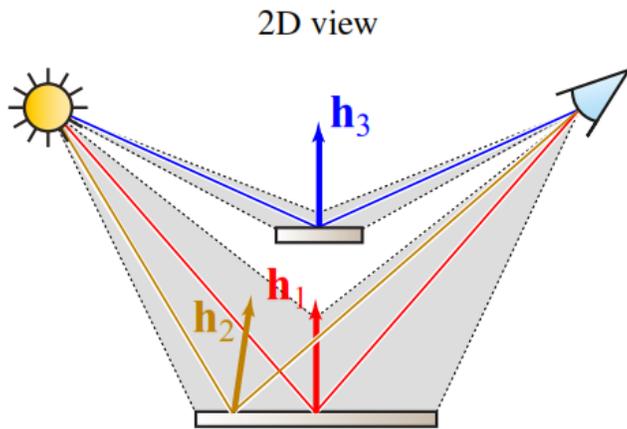
# Half vector space light transport

- ▶ change of domains, perform integration in different space:
  - ▶ product vertex area measure

$$I_j = \int_{\mathcal{P}} f(\mathbf{X}) d\mathbf{X}$$

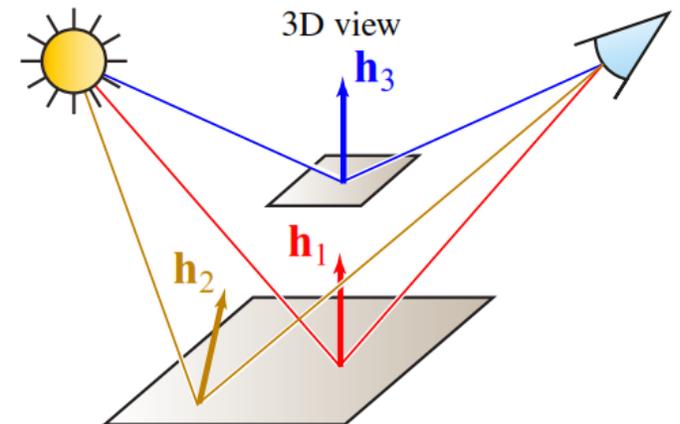
$$\mathbf{X} = (\mathbf{x}_0, \mathbf{x}_1, \dots, \mathbf{x}_{k-1}, \mathbf{x}_k)$$

- ▶ half vector space (fixed end points  $\mathbf{x}_0$  and  $\mathbf{x}_k$  and varying half vectors in between)



$$I_j = \int_{\Omega_h} f(\mathbf{X}(\mathbf{H})) \left| \frac{d\mathbf{X}}{d\mathbf{H}} \right| d\mathbf{H}$$

$$\mathbf{H} = (\mathbf{x}_0, \mathbf{h}_1, \dots, \mathbf{h}_{k-1}, \mathbf{x}_k)$$

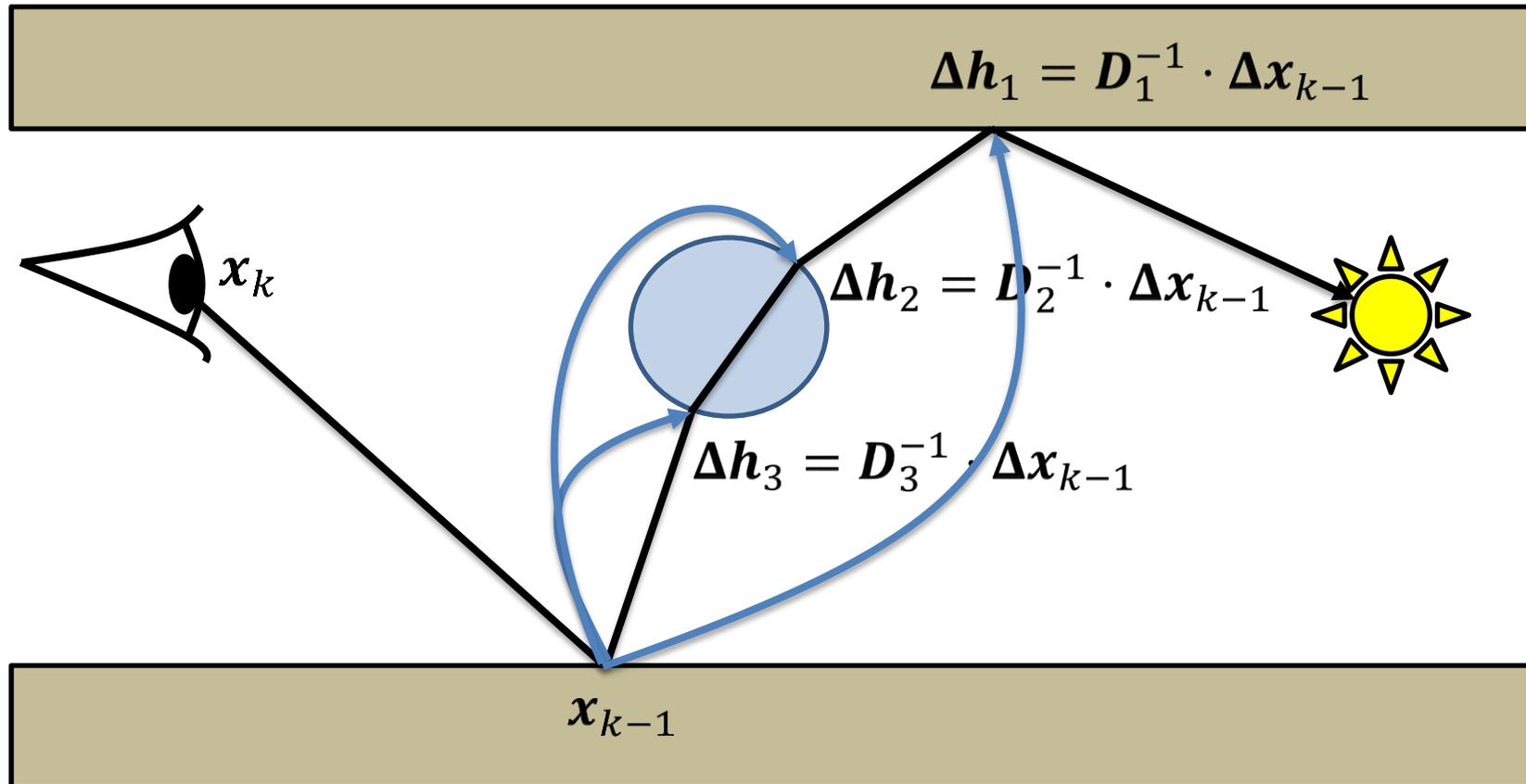


# Outline: **improved** half vector space light transport

- ▶ more natural space of constraints for half vectors
  - ▶ leads to more **precise ray differentials**
- ▶ support highly **detailed displacement**
  - ▶ new **half vector multi chain perturbation** on sub-paths
  - ▶ improves performance **samples/second**

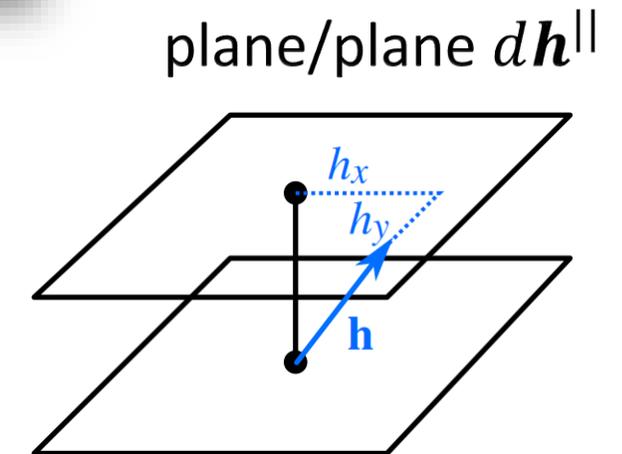
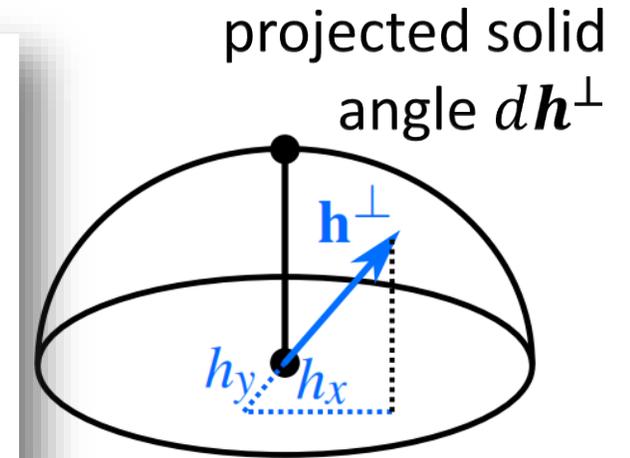
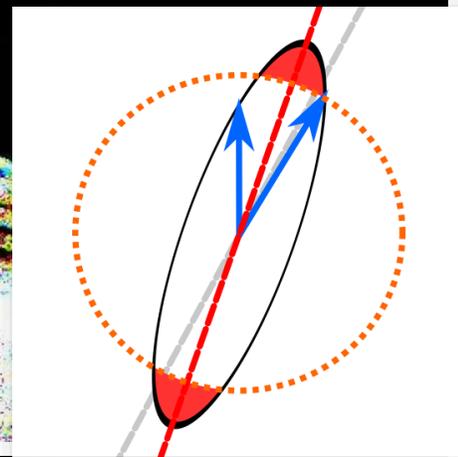
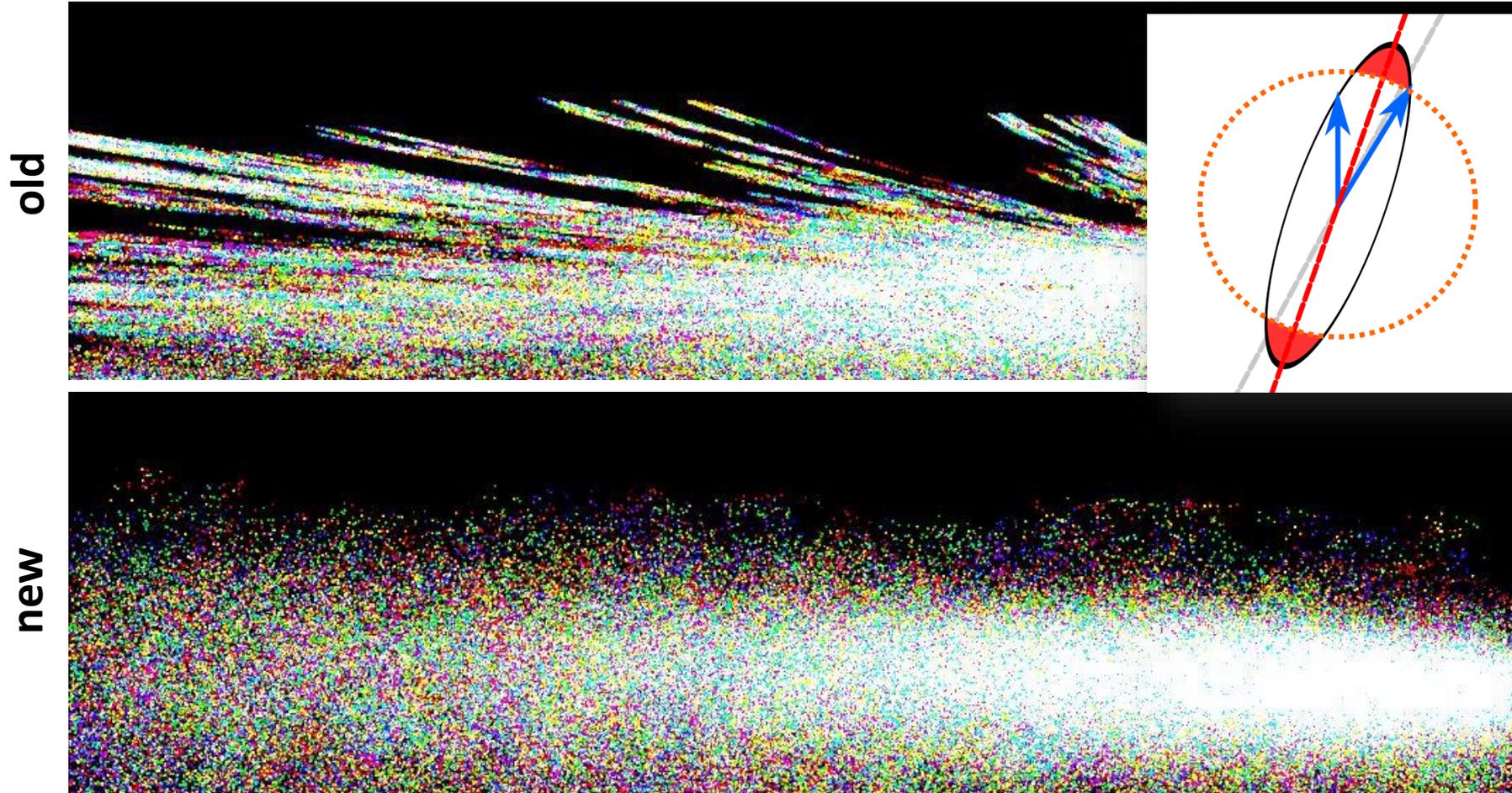
# Pixel stratification: ray differentials

- ▶ control image space stratification from half vector space!
- ▶ ray differential matrices  $D_i^{-1}$  transport vertex offset  $\Delta \mathbf{x}_{k-1}$  to half vectors  $\mathbf{h}_i$
- ▶ convert pixel footprint to half vector domain or vertex area at every vertex!
- ▶ derive pixel footprint based on geometry and BSDF scattering separately!



# Ray differentials and measure spaces

- ▶ projected solid angle has a bounded domain, plane/plane is unbounded
- ▶ need to cut off step size (first-order prediction!) at boundary, resulting in unwanted anisotropy
- ▶ plane/plane much more stable at grazing angle and for large step sizes

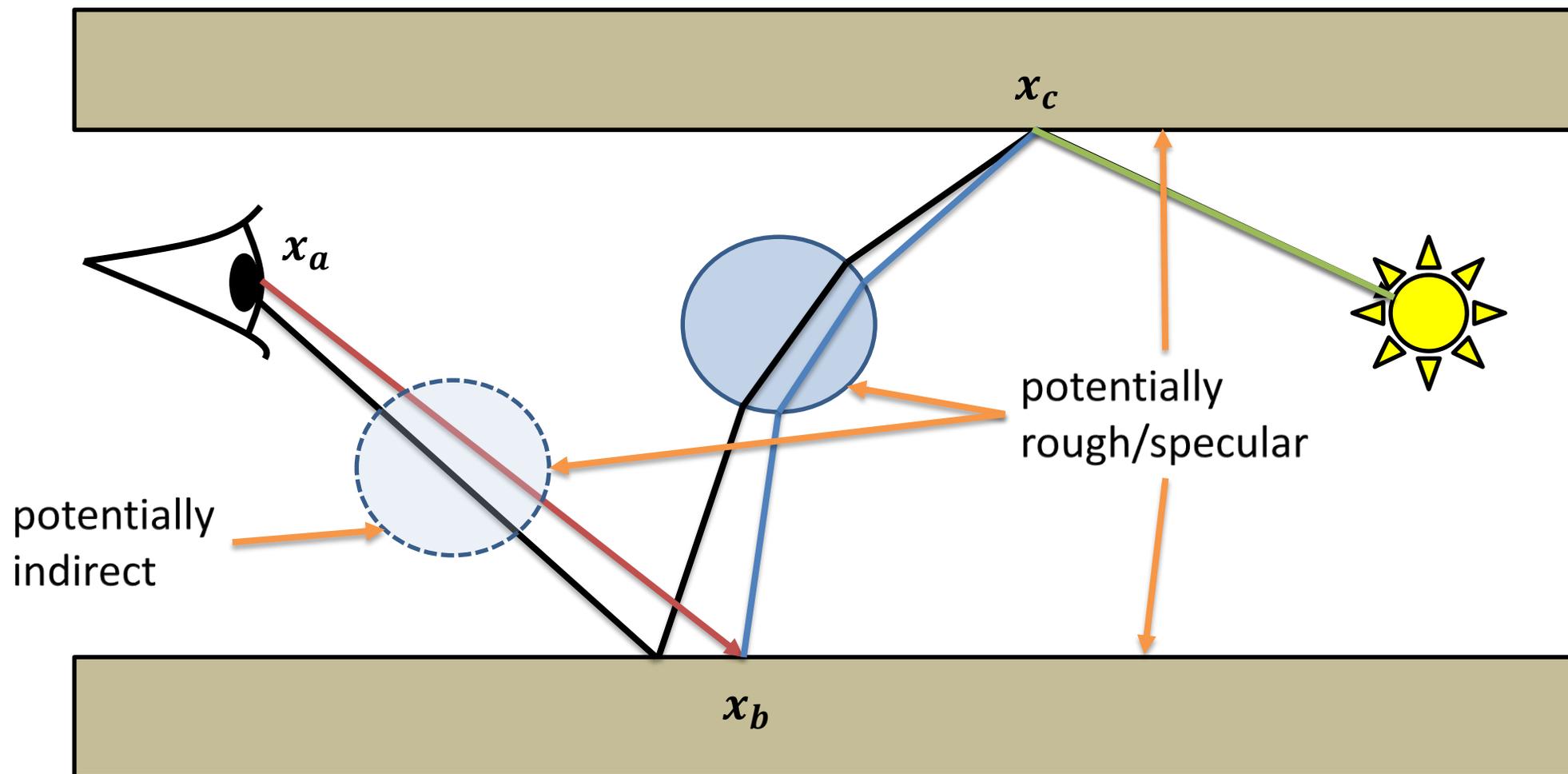


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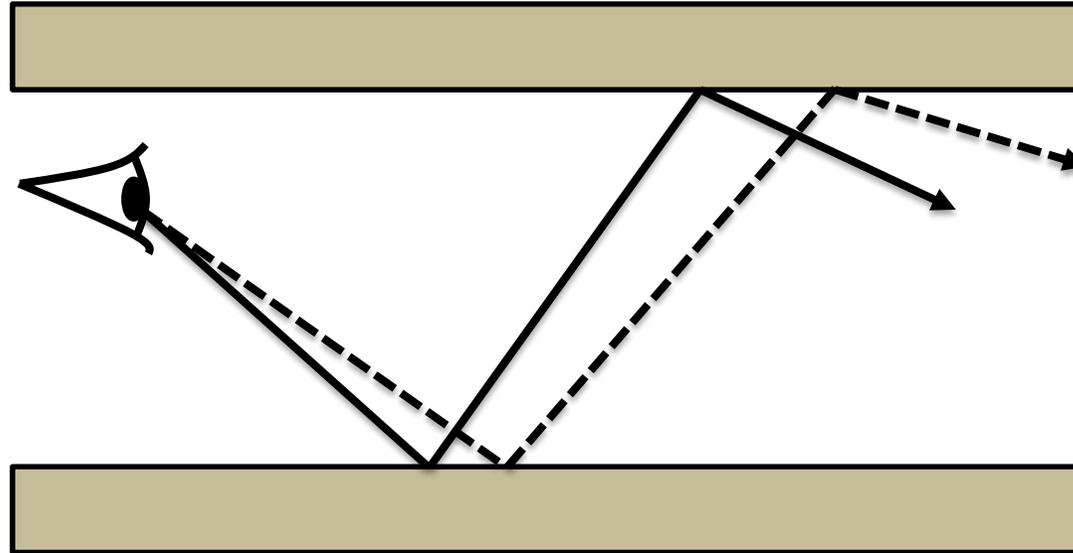
# Breaking up paths into segments (much the same as manifold exploration)

- ▶  $(x_a, \dots, x_b)$ : half vector multi chain perturbation (not half vector space, since end point moves!)
- ▶  $(x_b, \dots, x_c)$ : connect through ``specular chain`` only that nothing is strictly diffuse or specular
- ▶  $(x_c, \dots, x_0)$ : stays untouched



# Half vector multi chain perturbation

- ▶ do a pixel step, cast ray, perturb half vector, cast ray to resulting outgoing direction, iterate.
- ▶ essentially a perturbation of outgoing solid angles
- ▶ similar to Kelemen but in the Veach framework  
(half vector sampling is close to BSDF importance sampling)
- ▶ similar to Veach's multi chain but using half vectors  
(respecting BSDFs angular bandwidth precisely)



# Choice of breakup points $a, b, c$

- ▶  $a = k$  at the camera since we want to mutate the pixel coordinate
- ▶  $b$  at a vertex with high roughness, so BSDF evaluation will give a good contribution

$$P(x_i = x_b) \sim \alpha_i$$

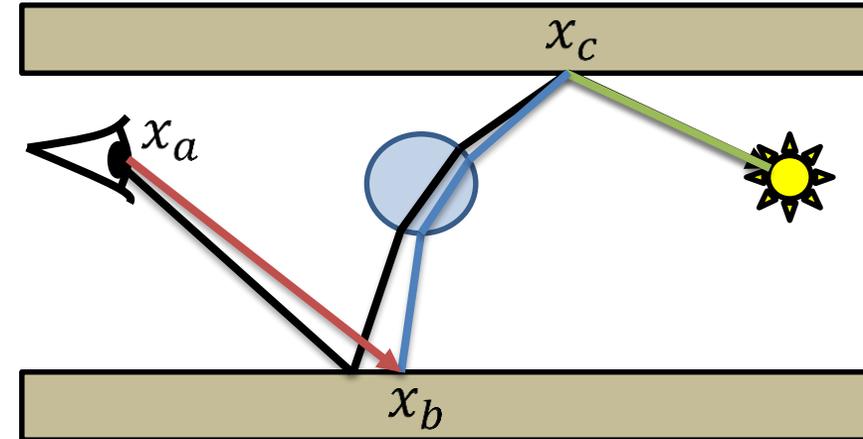
- ▶ mix in full multi chain and full half vector space (and normalise):

$$P(x_0 = x_b) = P(x_k = x_b) \sim 0.1$$

- ▶  $c$  at the light source for minimum correlation, but closer to  $a$  and  $b$  is faster and did not lead to artefacts in our experiments:

$$P(x_i = x_c) \sim \alpha_i \cdot \|x_i - x_{i+1}\|^2$$

- ▶ squared distance to penalise degenerate geometry terms



## Results: displaced geometry (skin, iris)

- ▶ 64spp, relatively lightweight 5M polygons but strongly varying geometric derivatives



**reference**  
**20h**

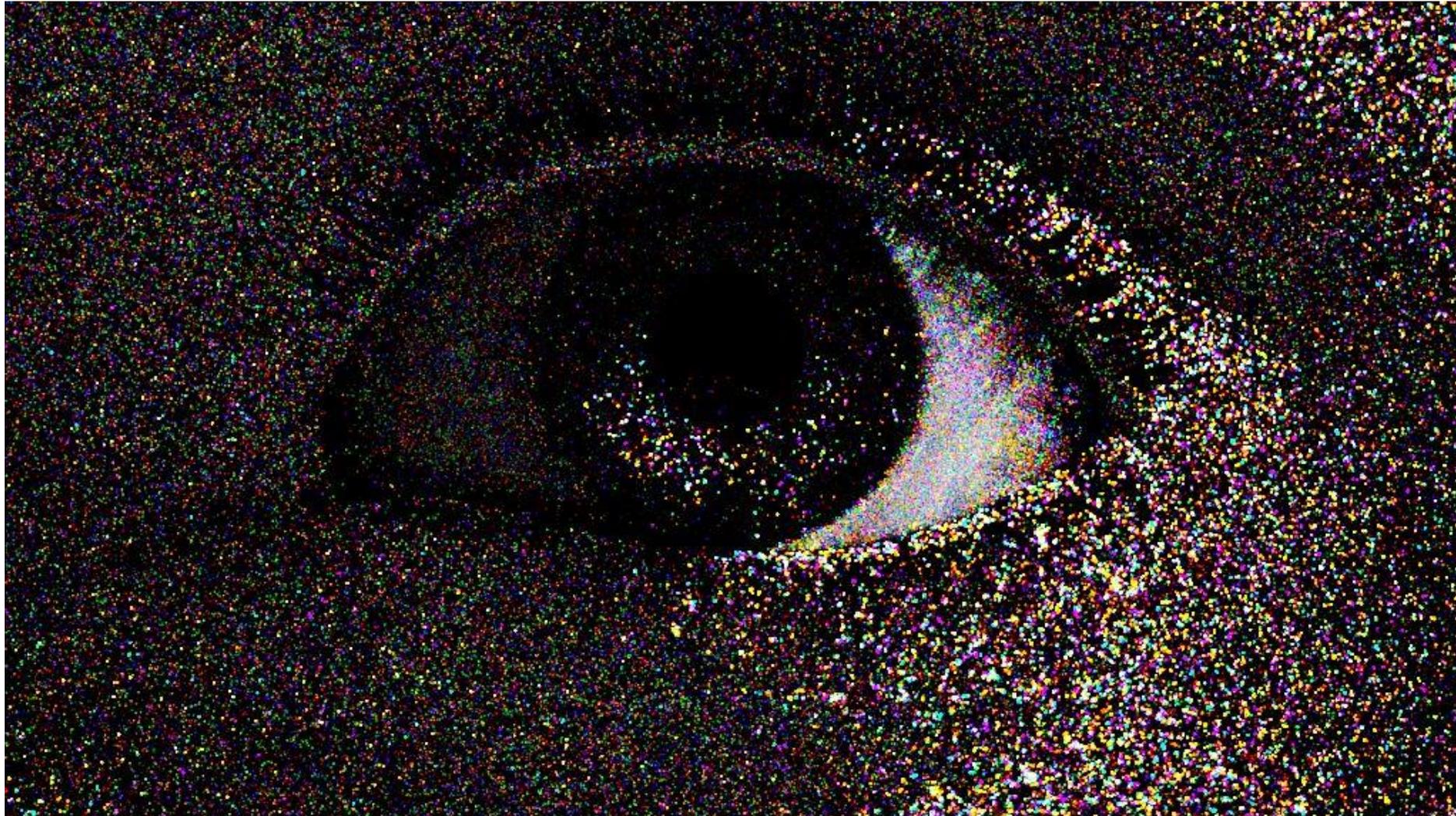
HSLT  
113s

HSLT 157s  
no displacement

improved  
HSLT 54s

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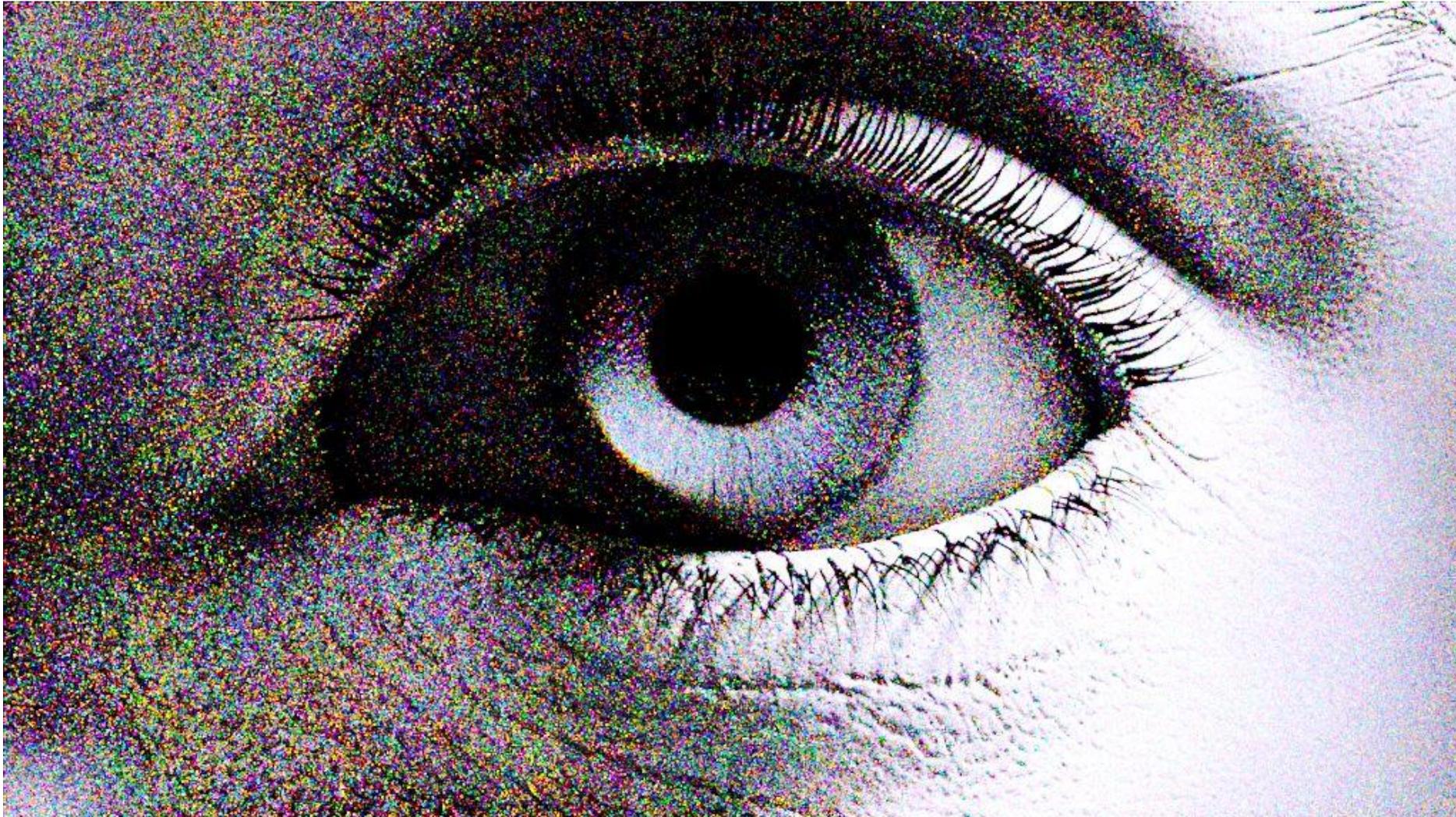
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20h

HSLT  
113s

HSLT 157s  
no displacement

**improved**  
**HSLT 54s**

## Results: long glossy chains

- ▶ jewellery: difficult since no clear breakup point (all surfaces are glossy or specular)
- ▶ we detect this robustly
- ▶ only moderately faster, since we choose full half vector space mutation most of the time



improved HSLT 40min 2067spp



HSLT 40min 1558spp

# Limitations and Future Work

- ▶ still need smooth surfaces for effective exploration using geometrical constraint derivatives
- ▶ no simple extension to participating media
  
- ▶ our choice of breakup points is simplistic
  - ▶ not using any differential geometry information to find breakup points yet
  - ▶ sub-optimal but good enough and fast to evaluate? (proof us wrong!)

# Conclusion

- ▶ made half vector space light transport more robust
  - ▶ more natural space of half vectors, Beckmann is a real Gaussian
  - ▶ leads to better step sizes and more precise ray differentials
  - ▶ better handling of displaced geometry
  - ▶ depth of field (see paper)
  - ▶ spectral/wavelength dependent (see paper)
- ▶ source code online: <https://www.mitsuba-renderer.org/repos/mitsuba.git>
  - ▶ still working on improving it though

**thank you for listening!**

**backup slides**

# Half vector space measurement

- ▶ simplified measurement with half vectors in projected solid angle [JM12, KHD14]

$$f(\mathbf{X}) \left| \frac{d\mathbf{X}}{d\mathbf{H}^\perp} \right| = \left| \frac{d\mathbf{o}_0^\perp}{d\mathbf{x}_k} \right| \prod_{i=1}^{k-1} f_r(\mathbf{i}_i, \mathbf{o}_i) \left| \frac{d\mathbf{o}_i}{d\mathbf{h}_i} \right| \left| \frac{\langle \mathbf{o}_i, \mathbf{n}_i \rangle}{\langle \mathbf{h}_i, \mathbf{n}_i \rangle} \right|$$

- ▶ in plane/plane:

transfer matrix [WMLT07]

$$f(\mathbf{X}) \left| \frac{d\mathbf{o}_0^\perp}{d\mathbf{x}_1} \right| \left| \frac{d\mathbf{x}_1}{d\mathbf{x}_k} \right| = G_1 \cdot |T_1| \prod_{i=1}^{k-1} f_r(\mathbf{i}_i, \mathbf{o}_i) \left| \frac{d\mathbf{o}_i}{d\mathbf{h}_i} \right| \left| \langle \mathbf{o}_i, \mathbf{n}_i \rangle \langle \mathbf{h}_i, \mathbf{n}_i \rangle^3 \right|$$

- ▶ don't divide the cosine, more numerically stable!

# Measurement for half vector multi chain perturbation

- ▶ simplified measurement in half vector space

$$f(\mathbf{X}) \left| \frac{d\mathbf{X}}{d\mathbf{H}} \right| = \left| \frac{d\mathbf{o}_0^\perp}{d\mathbf{x}_k} \right| \prod_{i=1}^{k-1} f_r(\mathbf{i}_i, \mathbf{o}_i) \left| \frac{d\mathbf{o}_i}{d\mathbf{h}_i} \right| |\langle \mathbf{o}_i, \mathbf{n}_i \rangle \langle \mathbf{h}_i, \mathbf{n}_i \rangle^3|$$

- ▶ half vector multi chain:

$$f(\mathbf{X}) \left| \frac{d\mathbf{X}}{d\mathbf{H}^o} \right| = \prod_{i=1}^{k-1} f_r(\mathbf{i}_i, \mathbf{o}_i) \left| \frac{d\mathbf{o}_i}{d\mathbf{h}_i} \right| |\langle \mathbf{o}_i, \mathbf{n}_i \rangle \langle \mathbf{h}_i, \mathbf{n}_i \rangle^3|$$

convert projected solid angle  
to plane/plane half vectors

- ▶ difference: last vertex free to move, do not require generalised geometric term

$$\left| \frac{d\mathbf{o}_0^\perp}{d\mathbf{x}_k} \right| = \left| \frac{d\mathbf{o}_0^\perp}{d\mathbf{x}_1} \right| \left| \frac{d\mathbf{x}_1}{d\mathbf{x}_k} \right| = G_1 \cdot |T_1|$$

- ▶ both only evaluated for the respective sub-path
- ▶ transition probability in half vector domain